## **Course Logistics**

- Project team member lists due this Sunday September 17th, 11:59 PM.
- Most teams should consist of 3 people.
- If you want to work individually, you need to send an email to me to get an approval.
- Discussion thread on Canvas to find teammates.
- For student paper presentations, please send me your slides by 2pm on the day of the presentation.

# SlowFast Networks for Video Recognition ICCV 2019

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### **Motivation**

Spatial (e.g., objects, scenes) and temporal (e.g., actions) cues might need different processing mechanisms.



## **Motivation**



"Neural mechanisms of form and motion processing in the primate visual system", Essen et al., Neuron, 1994

## **Two Stream CNNs**

- The first stream operates on a single RGB video frame.
- The second stream operates on optical flow computed between two adjacent video frames.



"Two-Stream Convolutional Networks for Action Recognition in Videos," Simonyan et al., NeurIPS 2014

### **SlowFast Networks**

- A two-pathway video recognition model where the slow pathway captures semantic spatial information.
- The fast pathway is a lot more lightweight than the slow pathway and it captures rapidly changing motion.
- Lateral connections fuse the two pathways.



#### **SlowFast Networks**

stage	Slow pathway	Fast pathway	output sizes $T \times S^2$
raw clip	-	-	$64 \times 224^2$
data layer	stride 16, 1 <sup>2</sup> stride 2, 1 <sup>2</sup>		Slow : $4 \times 224^2$ Fast : $32 \times 224^2$
conv <sub>1</sub>	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		$Slow: 4 \times 112^2$ Fast: $32 \times 112^2$
pool <sub>1</sub>	$\begin{array}{c cccc} 1 \times 3^2 \max & 1 \times 3^2 \max \\ \text{stride 1, } 2^2 & \text{stride 1, } 2^2 \end{array}$		$Slow: 4 \times 56^{2}$ Fast: 32×56 <sup>2</sup>
$res_2$	$\begin{bmatrix} 1 \times 1^2, 64 \\ 1 \times 3^2, 64 \\ 1 \times 1^2, 256 \end{bmatrix} \times 3$	$\begin{bmatrix} \frac{3\times1^2}{1\times3^2}, \frac{8}{1\times1^2}, \frac{8}{32}\\ 1\times1^2, \frac{32}{32} \end{bmatrix} \times 3$	$Slow: 4 \times 56^{2}$ Fast: 32×56 <sup>2</sup>
res3	$\begin{bmatrix} 1 \times 1^2, 128\\ 1 \times 3^2, 128\\ 1 \times 1^2, 512 \end{bmatrix} \times 4$	$\begin{bmatrix} \frac{3 \times 1^2, 16}{1 \times 3^2, 16} \\ 1 \times 1^2, \frac{64}{14} \end{bmatrix} \times 4$	$Slow: 4 \times 28^2$ Fast: 32 × 28 <sup>2</sup>
res <sub>4</sub>	$\begin{bmatrix} \frac{3 \times 1^2}{1 \times 3^2}, 256\\ 1 \times 1^2, 1024 \end{bmatrix} \times 6$	$\begin{bmatrix} \frac{3 \times 1^2}{1 \times 3^2}, \frac{32}{32}\\ 1 \times 1^2, \frac{128}{128} \end{bmatrix} \times 6$	$Slow: 4 \times 14^2$ Fast: 32×14 <sup>2</sup>
res5	$\begin{bmatrix} \frac{3 \times 1^2}{1 \times 3^2}, 512\\ 1 \times 1^2, 2048 \end{bmatrix} \times 3$	$\begin{bmatrix} \frac{3 \times 1^2, 64}{1 \times 3^2, 64} \\ 1 \times 1^2, 256 \end{bmatrix} \times 3$	$Slow: 4 \times 7^{2}$ Fast: $32 \times 7^{2}$
	global average pool, c	# classes	

## **Lateral Connections**

Feature tensor from the slow pathway







aT x S^2 x bC

- **Time-to-channel:** Feature tensor of shape (*a*T x S<sup>2</sup> x *b*C) is reshaped into (T, S<sup>2</sup>, *ab*C), i.e., all *a* frames are packed into the channel dimension.
- **Time-strided sampling:** Only one frame out of every *a* frames is sampled.
- **Time-strided convolution:** 3D convolution with stride *a* is applied.

Fusing Slow and Fast pathways with lateral connections is better than the Slow and Fast only baselines.

	lateral	top-1	top-5	GFLOPs
Slow-only	-	72.6	90.3	27.3
Fast-only	-	51.7	78.5	6.4
SlowFast	-	73.5	90.3	34.2
SlowFast	TtoC, sum	74.5	91.3	34.2
SlowFast	TtoC, concat	74.3	91.0	39.8
SlowFast	T-sample	75.4	91.8	34.9
SlowFast	T-conv	75.6	92.1	36.1

Varying values of  $\beta$ , the channel capacity ratio of the Fast pathway to make SlowFast lightweight.

	top-1	top-5	GFLOPs
Slow-only	72.6	90.3	27.3
$\beta = 1/4$	75.6	91.7	54.5
1/6	75.8	92.0	41.8
1/8	75.6	<b>92.1</b>	36.1
1/12	75.2	91.8	32.8
1/16	75.1	91.7	30.6
1/32	74.2	91.3	28.6

The proposed training recipe achieves comparable results without ImageNet pre-training.

model	pre-train	top-1	top-5	GFLOPs
3D R-50 [56]	ImageNet	73.4	90.9	36.7
3D R-50, recipe in [56]	-	69.4	88.6	36.7
3D R-50, our recipe	-	73.5	90.8	36.7

#### Comparison to the state-of-the-art

model	flow	pretrain	top-1	top-5	GFLOPs×views
I3D [5]		ImageNet	72.1	90.3	$108 \times N/A$
Two-Stream I3D [5]	1	ImageNet	75.7	92.0	$216 \times N/A$
S3D-G [61]	1	ImageNet	77.2	93.0	$143 \times N/A$
Nonlocal R50 [56]		ImageNet	76.5	92.6	$282 \times 30$
Nonlocal R101 [56]		ImageNet	77.7	93.3	$359 \times 30$
R(2+1)D Flow [50]	1	-	67.5	87.2	$152 \times 115$
STC [9]		-	68.7	88.5	$N/A \times N/A$
ARTNet [54]		-	69.2	88.3	$23.5 \times 250$
S3D [61]		-	69.4	89.1	$66.4 \times N/A$
ECO [63]		-	70.0	89.4	$N/A \times N/A$
I3D [5]	1	-	71.6	90.0	$216 \times N/A$
R(2+1)D [50]		-	72.0	90.0	$152 \times 115$
R(2+1)D [50]	1	-	73.9	90.9	$304 \times 115$
SlowFast 4×16, R50		•	75.6	92.1	36.1 × 30
<b>SlowFast</b> 8×8, R50		-	77.0	92.6	$65.7 \times 30$
SlowFast 8×8, R101		-	77.9	93.2	$106 \times 30$
SlowFast 16×8, R101		-	78.9	93.5	$213 \times 30$
SlowFast 16×8, R101+NL		-	79.8	93.9	$234 \times 30$

Accuracy vs. complexity tradeoff.



#### **Results on AVA**

#### Comparison to the state-of-the-art

model	flow	video pretrain	val mAP	test mAP
I3D [20]		Kinetics-400	14.5	-
I3D [20]	$\checkmark$	Kinetics-400	15.6	-
ACRN, S3D [46]	$\checkmark$	Kinetics-400	17.4	-
ATR, R50+NL [29]		Kinetics-400	20.0	-
ATR, R50+NL [29]	$\checkmark$	Kinetics-400	21.7	-
9-model ensemble [29]	$\checkmark$	Kinetics-400	25.6	21.1
I3D [16]		Kinetics-600	21.9	21.0
SlowFast		Kinetics-400	26.3	-
SlowFast		Kinetics-600	26.8	-
SlowFast, +NL		Kinetics-600	27.3	27.1
SlowFast*, +NL		Kinetics-600	28.2	-



## Summary

- A framework that achieves great results on a variety of action recognition datasets.
- Very effective optimization protocol for training video models from scratch.
- A nice extension to spatiotemporal localization task.