

# Discussion Questions

1. Can simulated data replace the real world data for autonomous driving? Computer vision?
2. How should the balance between real-world data and rendered synthetic data be optimized? Will the distribution gap between the generated synthetic data and the real-world data influence the model training?
3. Can simulated data be used to address the events from long-tail distribution (i.e., accidents, etc.)?
4. Is simulation truly necessary for autonomous driving?
5. Why is manual 3D asset creation problematic and how do authors tackle this issue? Any alternative ways to address these issues?
6. What are the advantages of using 3D information for placing new objects in existing images? Will future approaches also require explicit 3D modeling for this task?
7. Would the models trained on the GeoSim data generalize to scenarios in other countries?
8. Can GeoSim also incorporate other types of objects (i.e., cars, pedestrians, animals)?

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